

# Riemannian Geometry [Week 7]

Let  $(M, g)$  be a Riemannian manifold.

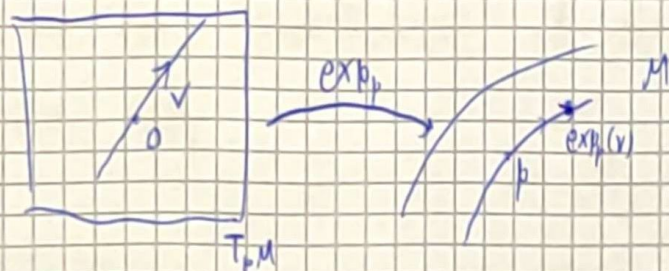
$\forall p \in M, v \in T_p M$ :  $\gamma_{p,v}(t)$  is the maximal geodesic

with  $\gamma(0) = p, \dot{\gamma}(0) = v$

Last time: We defined the exponential map

$$\exp_p: \Omega_p \subseteq T_p M \rightarrow M$$

$$\exp_p(tv) = \gamma_{p,v}(t)$$



We also proved that in a small neighborhood of  $v=0$ :

$\exp_p: U \rightarrow \exp_p(U) \subseteq M$  is a diffeomorphism on its image,

since  $\boxed{d\exp_p|_{v=0} = \text{id}_{T_p M}}$

- ~~Injectivity~~ Injectivity radius:

$$i(p) = \sup \left\{ r > 0 : \exp_p \text{ is a diffeo on its image when restricted to } B_r(0) = \{v : \|v\|_g < r\} \right\}$$

• ~~exp\_p~~ ~~exp\_p~~ ~~exp\_p~~ ~~exp\_p~~ ~~exp\_p~~ ~~exp\_p~~ ~~exp\_p~~ ~~exp\_p~~ ~~exp\_p~~ ~~exp\_p~~

- The map  $F: (p, v) \in TM \rightarrow (p, \exp_p(v)) \in M \times M$

defines a diffeomorphism from a neighborhood of the 0 section of  $TM$  to a neighborhood of the diagonal  $\Delta \subset M \times M$ .

## Normal coordinates

The coordinate system in which  $g$  looks as flat as possible.

Fix an orthonormal (with respect to  $g$ ) basis  $e_1, \dots, e_n$  of  $T_p M$ .

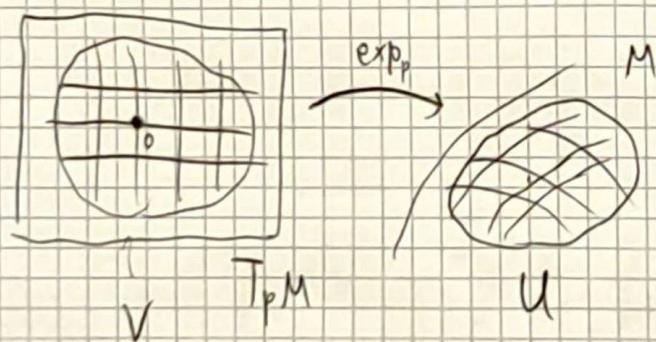
This fixes Cartesian coordinates on  $T_p M \cong \mathbb{R}^n$ :

$$\forall w \in T_p M, \quad w = w^i e_i$$

$\nwarrow$  Coordinates.

Normal coordinates in a neighborhood of  $p$  in  $M$

are the "push-forward" of the Cartesian coordinates on  $T_p M$  via  $\exp_p$ :



If  $U$  is a neighborhood of  $p$  in  $M$  such that  $\exp_p^{-1}$  is defined there:

$\forall q \in U$ , if  $q = \exp_p(v)$

$$x^i(q) = v^i = (\exp_p^{-1}(q))^i$$

$$\Rightarrow x^i(\exp_p(v)) = v^i$$

In these coordinates:  $\exp_p: V \rightarrow U$  is the identity

$$\text{And: } x^i(\exp_p(tv)) = t \cdot v^i \Rightarrow \gamma_{p,v}^i(t) = t \cdot v^i$$

(In these coordinates: Geodesics through  $p$  are straight lines)

### Proposition

In normal coordinates centered at  $p$ ,

$$g_{ij}(0) = \delta_{ij}, \quad \partial_i g_{jk}(0) = 0, \quad \Gamma_{ij}^k(0) = 0$$

(But in general:  $\partial^2 g(0) \neq 0 \Rightarrow$  this is related to the Riemann curvature tensor).

Proof: Since  $x^i(\exp_p(v)) = v^i \Rightarrow x^i(\exp_p(t \cdot e_j)) = t \cdot \delta_j^i$

So  $\forall j=0, 1, \dots, n$ , the curve

$t \mapsto \exp_p(t \cdot e_j)$  is the  $x^j$ -coordinate curve

$\Rightarrow \frac{\partial}{\partial x^j}$  is the tangent of this curve.

$$\text{So } \frac{\partial}{\partial x^j} \Big|_p = \frac{d}{dt} (\exp_p(t e_j)) \Big|_{t=0} = d\exp_p \Big|_{v=0} (e_j) = e_j$$

$$\text{So } g_{ij}(0) = g\left(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}\right) \Big|_p = g(e_i, e_j) = \delta_{ij}$$

since  $\{e_i\}_{i=1}^n$  is an orthonormal basis.

The curve  $\gamma_{p,v}(t) = \exp_p(tv)$  is a geodesic  $\forall v$ .

$\Rightarrow$  In normal coordinates:  $\gamma_{p,v}^k(t) = t \cdot v^k$

$$\text{So } \ddot{\gamma}_{p,v}^k(t) + \Gamma_{ij}^k(\gamma_{p,v}(t)) \cdot \dot{\gamma}_{p,v}^i \cdot \dot{\gamma}_{p,v}^j = 0$$

$$\Rightarrow \Gamma_{ij}^k(\gamma_{p,v}(t)) \cdot v^i v^j = 0 \stackrel{t=0}{\Rightarrow} \Gamma_{ij}^k(0) v^i v^j = 0 \quad \forall v \in T_p M$$

Since  $\Gamma_{ij}^k(0)$  is symmetric in  $i, j \Rightarrow \Gamma_{ij}^k(0) = 0$

And:  $\partial_k g_{ij} = \partial_k \langle \partial_i, \partial_j \rangle = \partial_k g_{aj} \Gamma_{ki}^a + g_{ai} \Gamma_{kj}^a$

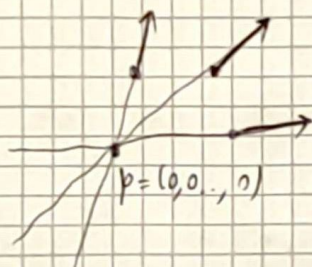
So  $\partial_k g_{ij}(0) = 0$



But we got more information from the proof:

$$\Gamma_{ij}^k(t \cdot v) \cdot v^i v^j = 0$$

So



The "radial" directions are special!!

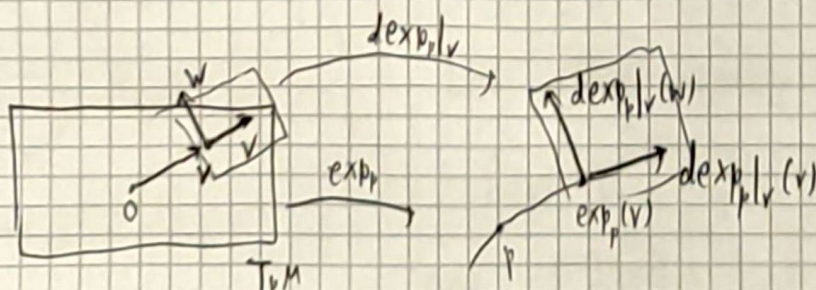
## The Gauss lemma.

Theorem: The exponential map satisfies the following properties:

a)  $\|d\exp_p|_v(v)\| = \|v\|$   
 $\underbrace{\phantom{d\exp_p|_v(v)}}_{\in T_{\exp_p(v)}M} \quad \underbrace{\phantom{v}}_{\in T_p M}$

b)  $\forall w \in T_v(T_p M)$  orthogonal to  $v$ , we have:

$$\langle d\exp_p|_v(v), d\exp_p|_v(w) \rangle = 0$$



The two statements can be combined as follows.

$$\forall v \in \Omega_p, \quad \forall w \in T_v \Omega_p: \quad \langle d\exp_p|_v(v), d\exp_p|_v(w) \rangle = \langle v, w \rangle$$

Remark: In normal coordinates,

$\nabla S = d\exp_p|_v(v)$  is just the radial vector field  
(At the point  $(x^1, \dots, x^n)$ ,  $S^i = x^i$ )

So the above says that  $g_{ij}^{(1)} x^i w^j = g_{ij} x^i w^j \quad \forall w$

$$\Rightarrow \boxed{g_{ij}(x) x^i = g_{ij} x^i}$$

Proof:

a) Recall:  $\exp_p(tv) = \gamma_{p,v}(t)$

$$\text{So } \dot{\gamma}_{p,v}(t) = \frac{d}{dt}(\exp_p(tv)) = d\exp_p|_{tv}(\dot{tv}) = d\exp_p|_{tv}(v)$$

$$\text{For } t=1: \dot{\gamma}_{p,v}(1) = d\exp_p|_v(v)$$

But  $\gamma_{p,v}$  is a geodesic, so  $\|\dot{\gamma}_{p,v}(t)\| = \|\dot{\gamma}_{p,v}(0)\| = \|v\|$ .

b) We will use the first variation formula for the length:

Without loss of generality,  $\|w\| = \|v\|$ .

$$\text{Let } \gamma(s) = \cos(s) \cdot v + \sin(s) \cdot w$$

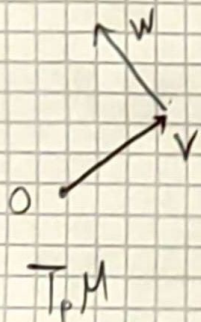
$$\gamma(0) = v, \quad \dot{\gamma}(0) = w$$

$$\text{and } \|\gamma(s)\| = \|v\| \quad (\text{since } v \perp w, \|v\| = \|w\|)$$

$$\text{If } \phi(t,s) = \exp_p(t \cdot \gamma(s)):$$

Variation of the curve  $\gamma_{p,v}(t)$

and  $\forall s: \phi_s(t)$  is a geodesic (acceleration = 0)



By 1<sup>st</sup> variation formula of the length:

$$\frac{d}{ds} l(\phi_s) \Big|_{s=0} = \frac{1}{l(\gamma_p)} \left\langle \frac{\partial \phi}{\partial s} \Big|_{s=0, t=1}, \dot{\gamma}(1) \right\rangle \quad (1)$$

$$\text{But: } l(\phi_s) = \int_0^1 \left\| \frac{\partial \phi_s}{\partial t} \right\| dt = \int_0^1 \|v\| dt = \|v\|$$

$$\text{And } \dot{\gamma}(1) = d\exp_p|_v(v)$$

$$\frac{\partial \phi}{\partial s} \Big|_{t=1} = \frac{\partial}{\partial s} (\exp_p(t \cdot \gamma(s))) \Big|_{t=1} = d\exp_p|_{\gamma(s)}(\dot{\gamma}(s))$$

$$\Rightarrow \frac{\partial \phi}{\partial s} \Big|_{s=0, t=1} = d\exp_p|_v(w)$$

$$\text{So } (1) \Rightarrow 0 = \langle d\exp_p|_v(v), d\exp_p|_v(w) \rangle \quad \square$$

In particular:

The exponential map send spheres centered at 0 in  $T_p M$  to surface orthogonal to the geodesics  $\gamma_{p,v}$



- We consider the normal coordinates on neighborhoods  $U$  of  $p$  which are normal (any  $q \in U$  can be connected with a geodesic segment to  $p$ ). Intersection of such neighborhoods: Convex neighborhood.

## Polar coordinates:

$$e_2 = 1$$

Instead of using Cartesian coordinates on  $T_p M$ , we could use polar coordinates and push them forward on  $M$  via  $\exp_p$ .

Assume  $\dim M = 2$ , and  $e_1, e_2$  orth. frame at  $p$ .

Let  $W_p = \exp_p(\{v \in T_p M : \|v\| < i(p)\})$

polar coordinates  $(r, \theta)$  on  $W_p \setminus \{p\}$ :

$$\left. \begin{aligned} x &= r \cdot \cos \theta \\ y &= r \cdot \sin \theta \end{aligned} \right\} \quad \begin{aligned} r &= \sqrt{x^2 + y^2} \\ \cos \theta &= \frac{x}{\sqrt{x^2 + y^2}} \end{aligned} \quad (x, y) \text{ Normal coordinates}$$

Proposition: In Polar coordinates:

$$g = dr^2 + b^2(r, \theta) d\theta^2,$$

$$g_{rr} = 1, \quad g_{r\theta} = 0$$

$$\text{and } \lim_{r \rightarrow 0} b(r, \theta) = 0, \quad \lim_{r \rightarrow 0} \frac{\partial b}{\partial r}(r, \theta) = 1.$$

Ex: On the flat plane:  $g_E = dr^2 + r^2 d\theta^2$

Proof: In polar coordinates:

$$\begin{aligned} q(r, \theta) &= \exp_p(r \cdot \cos \theta \cdot e_1 + r \cdot \sin \theta \cdot e_2) \\ &= \exp_p(r \cdot (\cos \theta e_1 + \sin \theta e_2)) \end{aligned}$$

So  $r \mapsto g(r, \theta)$  is a geodesic

~~Then~~ Geodesic tangent vector:  $\frac{\partial}{\partial r}$

So  $\|\frac{\partial}{\partial r}\| = \text{const}$ . As  $r \rightarrow 0$ :  $\|\frac{\partial}{\partial r}\| = \|\cos \theta \cdot e_1 + \sin \theta \cdot e_2\| = 1$

So  $g_{rr} = 1$  everywhere.

and:  ~~$\frac{\partial}{\partial r} = \cos \theta \cdot e_1 + \sin \theta \cdot e_2$~~

$$\frac{\partial}{\partial r} \Big|_{\exp_p(v)} = d\exp_p \Big|_{\exp_p(v)} (\cos \theta \cdot e_1 + \sin \theta \cdot e_2)$$

$$\frac{\partial}{\partial \theta} \Big|_{\exp_p(v)} = d\exp_p \Big|_{\exp_p(v)} (r \cdot (-\sin \theta \cdot e_1 + \cos \theta \cdot e_2))$$

By Gauss-lemma:  $\langle \frac{\partial}{\partial r}, \frac{\partial}{\partial \theta} \rangle = 0$ .

~~So~~ So:  $g = dr^2 + b^2 \cdot d\theta^2$ ,  $b = \|\frac{\partial}{\partial \theta}\|$

By change of coordinates:

$$\frac{\partial}{\partial r} = \cos \theta \frac{\partial}{\partial x} + \sin \theta \frac{\partial}{\partial y}$$

$$\frac{\partial}{\partial \theta} = -r \sin \theta \frac{\partial}{\partial x} + r \cos \theta \frac{\partial}{\partial y}$$

So  $\frac{b(r, \theta)}{r} = \sqrt{g_{xx} \sin^2 \theta + 2g_{xy} \cos \theta \cdot \sin \theta + g_{yy} \cos^2 \theta}$

At  $r > 0$ :  $g_{ij} = \delta_{ij}$ ,  ~~$\frac{b(r, \theta)}{r} \rightarrow 1$~~

So  $\frac{b(r, \theta)}{r} \rightarrow 1 \quad \forall \theta$

